REGULARISATION OF ILL-POSED ALGEBRAIC SYSTEMS

YANG YANG

Novosibirsk, Russian

e-mail: y.yan1@g.nsu.ru

The solution of ill-posed systems of linear equations has been an active and important area of research.

We discuss:

$$Az = u$$
, $z \in Z = \mathbb{R}^n$, $u \in U = \mathbb{R}^n$. (1)

- If it is well-conditioned, i.e., the number of conditions is small, the solution of equation
 is stable with respect to the perturbation of the right terminal term; thus the problem is well-posed
- (2) If it is ill-posed, i.e., when the condition number is very large, a small change in the right-hand term u will cause a large deviation of the approximate solution from the true solution, and thus equation (1) is ill-posed.

Theorem 1. The vector $x_T \in U$ is said to be a regular fitting solution to the system of equations (1), which satisfies

$$||x_T|| = \min_{u \in U} ||u||$$
.

Theorem 2.Let A be a continuous operator from the metric space F to the metric space U. Then $\forall \alpha > 0$ and $\forall u \in U, \exists z_{\alpha} \in F_1$ such that the generalized function

$$M^{\alpha}[z, u] = \rho_u^2(Az, u) + \alpha\Omega[z], u \in U, z \in F_1 \subset F$$

reaches its lower exact bound at z_{α} , i.e.

$$M^{\alpha}[z_{\alpha}, u] = \inf_{z \in F_1} M^{\alpha}[z, u].$$

Theorem 3.The eigenvalues of $\tilde{A}^T\tilde{A}$ are $\bar{\lambda}_1, \bar{\lambda}_2, \dots, \bar{\lambda}_n$. For A^TA the size of the eigenvalue perturbation is the same as $\|A - \tilde{A}\|$.

Keywords: Stabilization functional, Regularization, Inverse problems, Regularization parameter.

AMS Subject Classification: 86-08 Computational methods for problems pertaining to geophysics

REFERENCES

- Tikhonov., On Stability of Inverse Problems, Dokl Acad. Nauk USSR 39(5), 1943, 195-198 p.
- Wang, Yu., Xiao., Numerical solution of inverse problems, Science Publishers, 2003, 179-183 p.